

## Flow sensor (anemometer), 29008 Dofs, 1 to 3 parameters

Example with 1 parameter:

$$G(p) = c((sE - A_{v0} - p(A_{v1} - A_{v0}))^{-1}b)$$

with fluid velocity  $p(=v) \in [0, 1]$  as single parameter and output as difference between the two sensors:

$$C(1, 173) = 1, \quad C(1, 133) = -1$$

permutation:

$$C = CP^T$$

for simulation:  $u$  is heater with step function (at id 35)

The following matrices are available:

- \*.B load vector
- \*.E damping matrix
- \*.C permutation matrix (matrices built with ANSYS, for adapting nodes and dofs)
- \*.A stiffness matrices
- \_v0 diffusion
- \_v1 diffusion and convection

Use mmread for reading the matrices into matlab.

Example with 3 parameters: (infos about the matrices were extracted from IMTEK Mathematica code)

$$G(p_0, p_1, p_2) = c((\underbrace{s(M_s + p_0 M_f)}_{E(p_0)} - \underbrace{(A_{d,s} + p_1 A_{d,f} + p_2 A_c)}_{A(p_1, p_2)})^{-1} b)$$

with parameters:

$$\begin{array}{ll} p_0 \in [0, 1] & (c - \text{specific heat}) \\ p_1 \in [0.1, 2] & (\kappa - \text{thermal conductivity}) \\ p_2 \in [1, 2] & (cv - \text{specific heat fluid velocity}) \\ \rho & (\text{mass density}) \text{ seems to be fixed } (\rho = 1?) \end{array}$$

and matrices:

$$\begin{array}{ll} M_s & = \text{model\_0\_1\_1.E} \\ M_f & = \text{model\_0\_2\_1.E} - M_s \\ A_{d,s} & = \text{model\_0\_1\_1.A} \\ A_{d,f} & = \text{chop}(\text{model\_1\_1\_1.A} - A_{d,s}) + \text{chop}(\text{model\_1\_2\_2.A} - \text{model\_1\_2\_1.A}) \\ A_c & = \text{model\_0\_2\_1.A} - A_{d,s} \\ b & = \text{model\_0\_1\_1.B} \end{array}$$

Infos from IMTEK: Take care of too small numbers (otherwise you will obtain illconditioned matrices) Thus, filter them out:

Mathematica: Chop[expr, delta] replaces numbers smaller in absolute magnitude than delta by 0. Chop uses a default tolerance of  $10^{-10}$   
matlab (chop = ):

$$A = A .* (abs(A) >= 10^{-12});$$